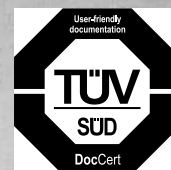




SEW
EURODRIVE

Compact Operating Instructions



MOVITRAC[®] B





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1 General Information

1.1 Scope of this documentation

This documentation comprises the general safety notes and a selected information regarding the device.

- Please note that this documentation does not replace the detailed operating instructions.
- Read the detailed operating instructions before you start working with the device.
- Observe the information, instructions and notes in the detailed operating instructions. This is essential for fault-free operation of the unit and fulfillment of any rights to claim under warranty.
- The enclosed CD or DVD contains PDF files of the additional operating instructions as well as further documentation regarding the device.
- All technical documentation from SEW-EURODRIVE is available as individual PDF files via the SEW-EURODRIVE website.

1.2 Structure of the safety notes

1.2.1 Meaning of the signal words

The following table shows the grading and meaning of the signal words for safety notes, notes on potential risks of damage to property, and other notes.

Signal word	Meaning	Consequences if disregarded
▲ DANGER	Imminent danger	Severe or fatal injuries
▲ WARNING	Possible dangerous situation	Severe or fatal injuries
▲ CAUTION	Possible dangerous situation	Minor injuries
NOTICE	Possible damage to property	Damage to the drive system or its environment
INFORMATION	Useful information or tip: Simplifies the handling of the drive system.	–

1.2.2 Structure of the section-related safety notes

Section-related safety notes do not apply to a specific action, but to several actions pertaining to one subject. The used symbols indicate either a general or a specific hazard.

This is the formal structure of a section-related safety note:



▲ SIGNAL WORD

Type and source of danger.

Possible consequence(s) if disregarded.

- Measure(s) to prevent the danger.



1.2.3 Structure of the embedded safety notes

Embedded safety notes are directly integrated in the instructions just before the description of the dangerous action.

This is the formal structure of an embedded safety note:

- **▲ SIGNAL WORD** Nature and source of hazard.
Possible consequence(s) if disregarded.
 - Measure(s) to prevent the danger.



2 Safety Notes

The following basic safety notes must be read carefully to prevent injury to persons and damage to property. The operator must ensure that the basic safety notes are read and adhered to. Make sure that persons responsible for the plant and its operation, as well as persons who work independently on the unit, have read through the operating instructions carefully and understood them. If you are unclear about any of the information in this documentation, or if you require further information, please contact SEW-EURO-DRIVE.

2.1 Preliminary information

The following safety notes predominantly refer to the use of frequency inverters. Additionally, when using drives with motors or gearmotors, observe the corresponding safety notes in the respective operating instructions.

Please also observe the supplementary safety notes in the individual sections of this publication.

2.2 General information

During operation, frequency inverters can have live, bare parts according to their degree of protection.

Severe or fatal injuries.

- All work related to transportation, storage, setup/mounting, connection, startup, maintenance and repair may only be carried out by qualified personnel, in strict observance of:
 - The relevant detailed operating instructions
 - The warning and safety signs on the motor/gearmotor
 - All other project planning documents, operating instructions and wiring diagrams related to the drive
 - The specific regulations and requirements for the system
 - The national/regional regulations governing safety and the prevention of accidents
- Never install damaged products.
- Submit a complaint to the shipping company immediately in the event of damage.

Removing covers without authorization, improper use as well as incorrect installation or operation may result in severe injuries to persons or damage to property.

This document provides further information.



2.3 Target group

Any mechanical work may only be performed by adequately qualified personnel. Qualified personnel in this context are persons who are familiar with the setup, mechanical installation, trouble shooting and maintenance for this product. Further, they are qualified as follows:

- Training in mechanical engineering, e.g. as a mechanic or mechatronics technician (final examinations must have been passed).
- They are familiar with these operating instructions.

Any electronic work may only be performed by adequately qualified electricians. Qualified electricians in this context are persons who are familiar with the electronic installation, startup, trouble shooting and maintenance for this product. Further, they are qualified as follows:

- Training in electrical engineering, e.g. as an electrician or mechatronics technician (final examinations must have been passed).
- They are familiar with these operating instructions.

All work in further areas of transportation, storage, operation and waste disposal must only be carried out by persons who are trained appropriately.

2.4 Designated use

Frequency inverters are components for controlling asynchronous AC motors. Frequency inverters are components intended for installation in electrical systems or machines. Never connect capacitive loads. Operation with capacitive loads results in over-voltages and may destroy the unit.

The following standards apply if the frequency inverters are marketed in the EU/EFTA:

- In case of installation in machines, startup of the drive inverters (meaning the start of proper use) is prohibited until it is determined that the machine meets the requirements stipulated in Directive 2006/42/EC (machine directive); observe EN 60204.
- Startup (i.e. the start of designated use) is only permitted under observance of the EMC (2004/108/EC) directive.
- The frequency inverters comply with the requirements of the Low Voltage Directive 2006/95/EC. The harmonized standards of the EN 61800-5-1/DIN VDE T105 series in connection with EN 60439-1/VDE 0660 part 500 and EN 60146/VDE 0558 are applied to these frequency inverters.

Observe the technical data and the connection requirements specified on the nameplate and the operating instructions.

**2.4.1 Safety functions**

Frequency inverters from SEW-EURODRIVE must not perform any safety functions unless the inverters are subordinate to other safety systems.

Use higher-level safety systems to ensure protection of equipment and personnel.

When using the "Safe stop" function, you must observe the following publications:

- MOVITRAC® B / functional safety

This documentation is available via "Documentation \ Software \ CAD" on the **SEW-EURODRIVE web site**.

2.4.2 Content of this publication

This publication contains conditions and amendments related to MOVITRAC® B in safety-oriented applications.

The system comprises a frequency inverter with asynchronous motor and safety-tested external disconnecting device.

2.5 Applicable documentation

This document supplements the MOVITRAC® B operating instructions and limits the application notes according to the following information.

It can only be used in conjunction with the following publications:

- MOVITRAC® B compact operating instructions
- MOVITRAC® B communication manual
- The respective manual of the used option card

2.6 Transport / storage

Inspect the shipment for any damage that may have occurred in transit as soon as you receive the delivery. Inform the shipping company immediately. It may be necessary to preclude startup. Observe the climate conditions according to chapter "General technical data".



2.7 Installation

The units must be installed and cooled according to the regulations and specifications in this documentation.

Protect the frequency inverters from excessive strain. Do not twist any components and do not modify the insulation spaces. Do not touch any electronic components or contacts.

Frequency inverters contain components that can easily be damaged by electrostatic energy and improper handling. Electric components must not be mechanically damaged or destroyed.

The following applications are prohibited unless the unit is explicitly designed for such use:

- Use in potentially explosive atmospheres.
- Use in areas exposed to harmful oils, acids, gases, vapors, dust, radiation, etc. (frequency inverter may only be operated in climate class 3K3 to EN 60721-3-3)
- Use in non-stationary applications which are subject to mechanical vibration and impact loads in excess of the requirements in EN 61800-5-1.

2.8 Electrical connection

Observe the applicable national accident prevention guidelines when working on live frequency inverters (e.g. BGV A3 for Germany).

During installation, observe the specifications regarding cable cross sections, fusing and protective conductor connection. This publication contains additional information.

In this documentation, you will find notes on EMC-compliant installation, such as shielding, grounding, arrangement of filters and routing of lines. The manufacturer of the system or machine is responsible for maintaining the limits established by EMC legislation.

Protective measures and protection devices must comply with the regulations in force (e.g. EN 60204 or EN 61800-5-1).

Ground the unit.

2.9 Safe disconnection

The unit meets all requirements for safe disconnection of power and electronic connections in accordance with EN 61800-5-1. All connected circuits must also satisfy the requirements for safe disconnection.



2.10 Operation

Systems with integrated frequency inverters must be equipped with additional monitoring and protection devices, as applicable, according to the relevant safety guidelines and regulations, such as legislation governing technical equipment, accident prevention regulations, etc.

Do not touch live components or power connections until 10 minutes after disconnecting the frequency inverters from the supply voltage because there may still be some charged capacitors. Observe the corresponding labels on the frequency inverter.

Keep all covers and housings closed during operation.

The fact that the status LED and other display elements are no longer illuminated does not indicate that the unit has been disconnected from the supply system and no longer carries any voltage.

Mechanical blocking or safety functions inside the unit may cause a motor standstill. Eliminating the cause of the problem or performing a reset may an automatic restart. If, for safety reasons, this is not permitted for the driven machine, disconnect the unit from the supply system before correcting the error.

2.11 Unit temperature

MOVITRAC® B frequency inverters are usually operated with braking resistors. The braking resistors are usually installed on the control cabinet.

The braking resistors can reach a surface temperature of significantly more than 70 °C.

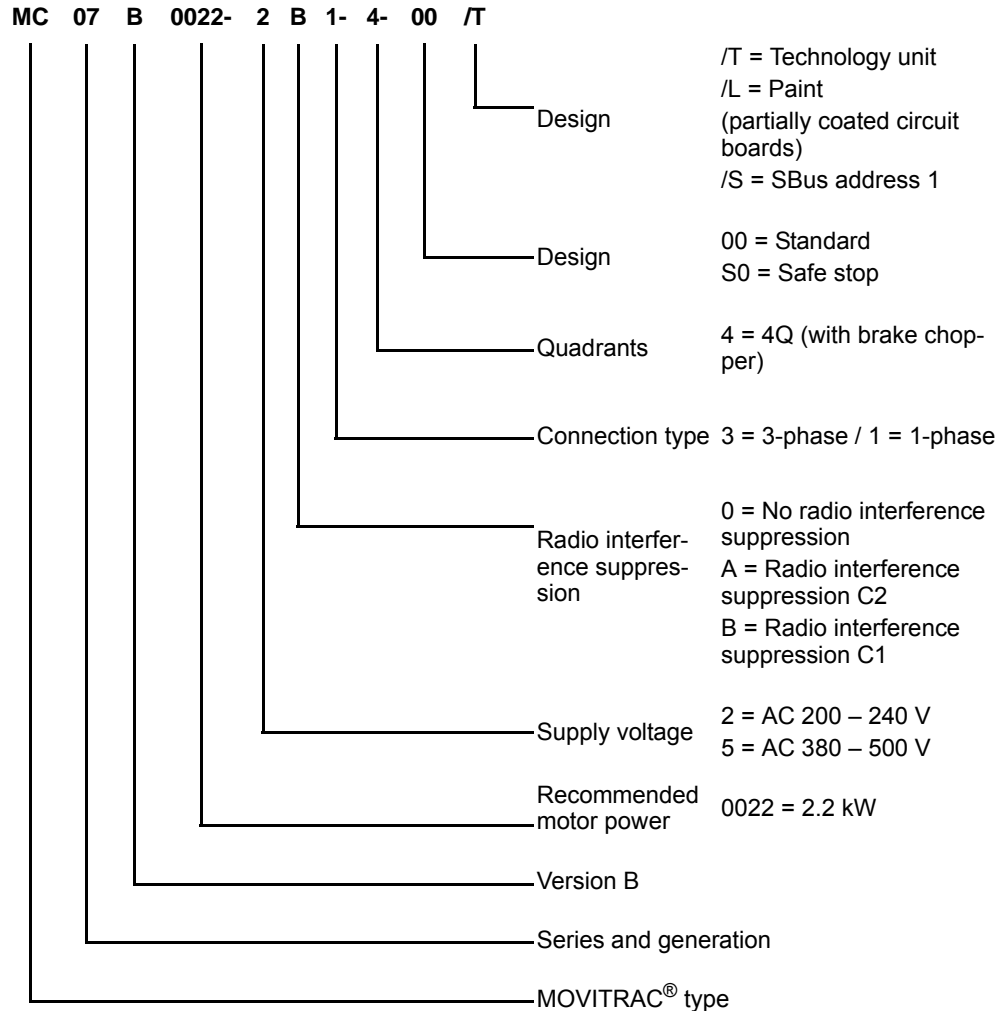
Never touch the braking resistors during operation or in the cool-down phase once the unit has been switched off.



3 Unit Designation / Nameplate

3.1 Type designation

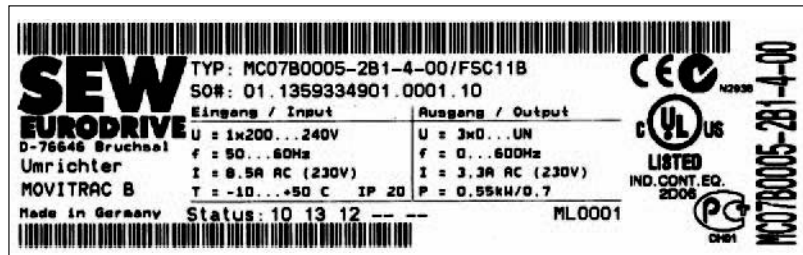
The following diagram shows a type designation:





3.2 Nameplate

The following figure shows a nameplate:



3185547659

Input	U	Rated line voltage
	I	Rated line current, 100% operation
	f	Nominal line frequency
Output	U	Output voltage 100% operation
	I	Nominal output current 100% operation
	f	Output frequency
T		Ambient temperature
P motor		Recommended motor power 100% operation

The unit status is indicated above the lower barcode. It documents the hardware and software states of the unit.



4 Installation



DANGER

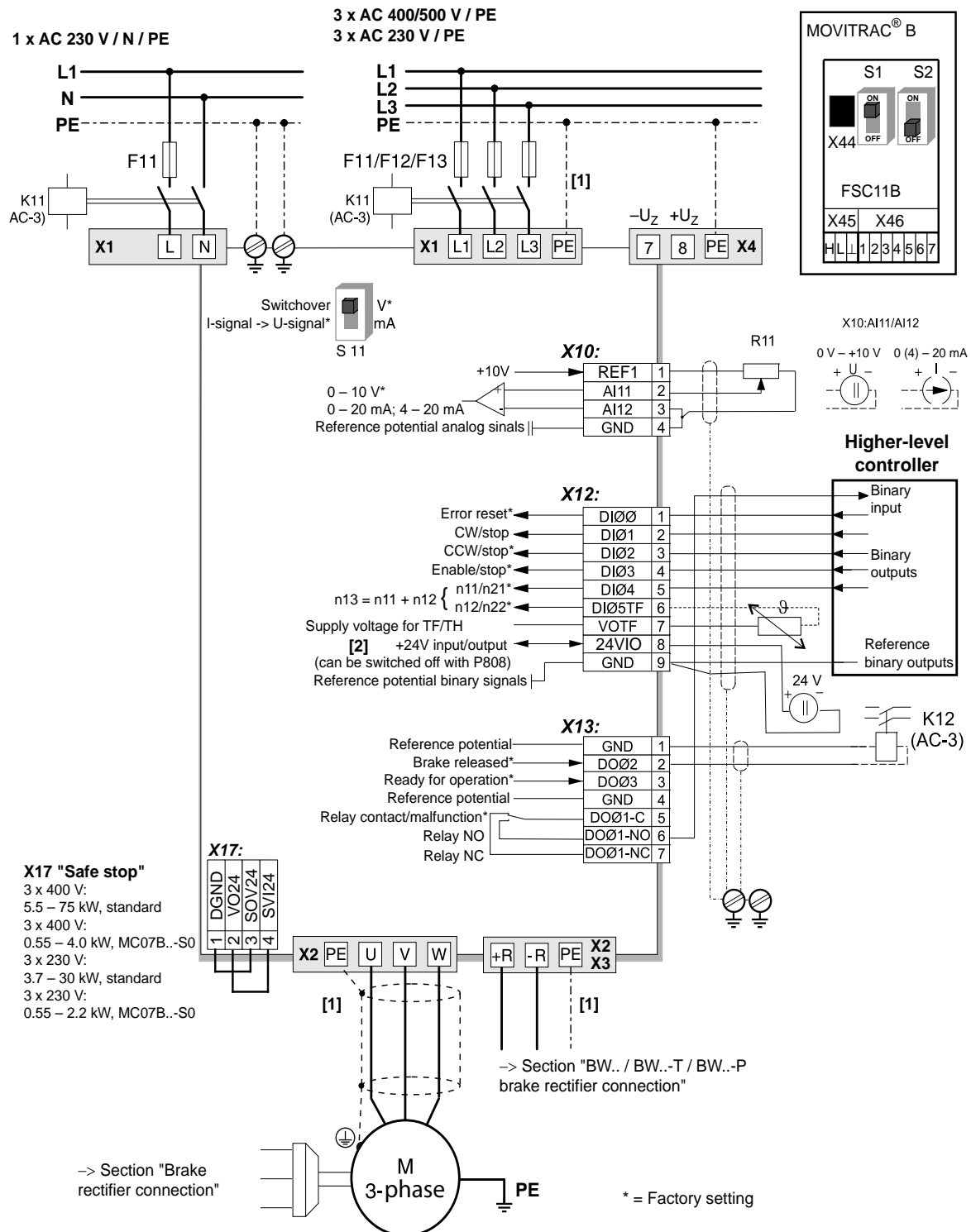
The surface temperatures of the heat sinks can exceed 70 °C.

Danger of burns.

- Do not touch the heat sink.



4.1 Wiring diagram



- [1] In sizes 1, 2S, and 2, there is no PE connection next to the power supply connection terminals and motor connection terminals [X1]/[X2]. Use the PE terminal next to the DC link connection [X4] (only size 1 – 5). For size 0, the plate is the PE connection.
- [2] The MC07B...S0 unit type must always be supplied with external voltage.

X4 is only available in sizes 1 – 5. From size 3 onwards, there are two additional PE terminals.



5 Startup

5.1 Startup with factory setting – brief description

You can directly connect the MOVITRAC® B frequency motor to a motor with the same power rating. For example: A 1.5 kW (2.0 HP) motor can be connected directly to a MC07B0015.

5.1.1 Procedure

1. Connect the motor to MOVITRAC® B (terminal X2).
2. You have the option of connecting a braking resistor (terminal X2/X3).
3. The following signal terminals must be controlled with your control system:
 - Enable DIØ3
 - As required: CW/STOP DIØ1 or CCW/STOP DIØ2
 - Setpoint:
 - Analog input (X10) and/or
 - DIØ4 = n11 = 150 rpm and/or
 - DIØ5 = n12 = 750 rpm and/or
 - DIØ4 + DIØ5 = n13 = 1500 rpm
 - For brakemotors:
DOØ2 = brake control via brake rectifiers
4. You have the option of connecting the following signal terminals:
 - DIØØ = error reset
 - DOØ1 = /malfunction (designed as a relay contact)
 - DOØ3 = ready
5. Check the controller for the required functionality.
6. Connect the frequency inverter to the mains (X1).

5.1.2 Notes

Signal terminal functions and setpoint settings can be modified using the FBG11B keypad or a PC. A PC connection requires the FSC11B front option or one of the following interface adapters: UWS21B / UWS11A / USB11A.



5.2 Manual operation with FBG11B speed control module

FBG11B speed control module of the keypad (local manual operation): LED  flashes.

The only relevant parameters in "FBG speed control module" operating mode are:

- *P122 Direction of rotation FBG manual operation*
- RUN key and STOP/RESET key
- Speed control module (potentiometer)

When the FBG speed control module is activated, the symbol flashes.

You limit the smallest speed with *P301 Minimum speed* and the largest speed with the n_{\max} symbol.

After an error, a reset can be performed using the STOP/RESET button via the terminal or the interface. After a reset, the "manual setpoint generator" operating mode will be active again. The drive remains stopped.

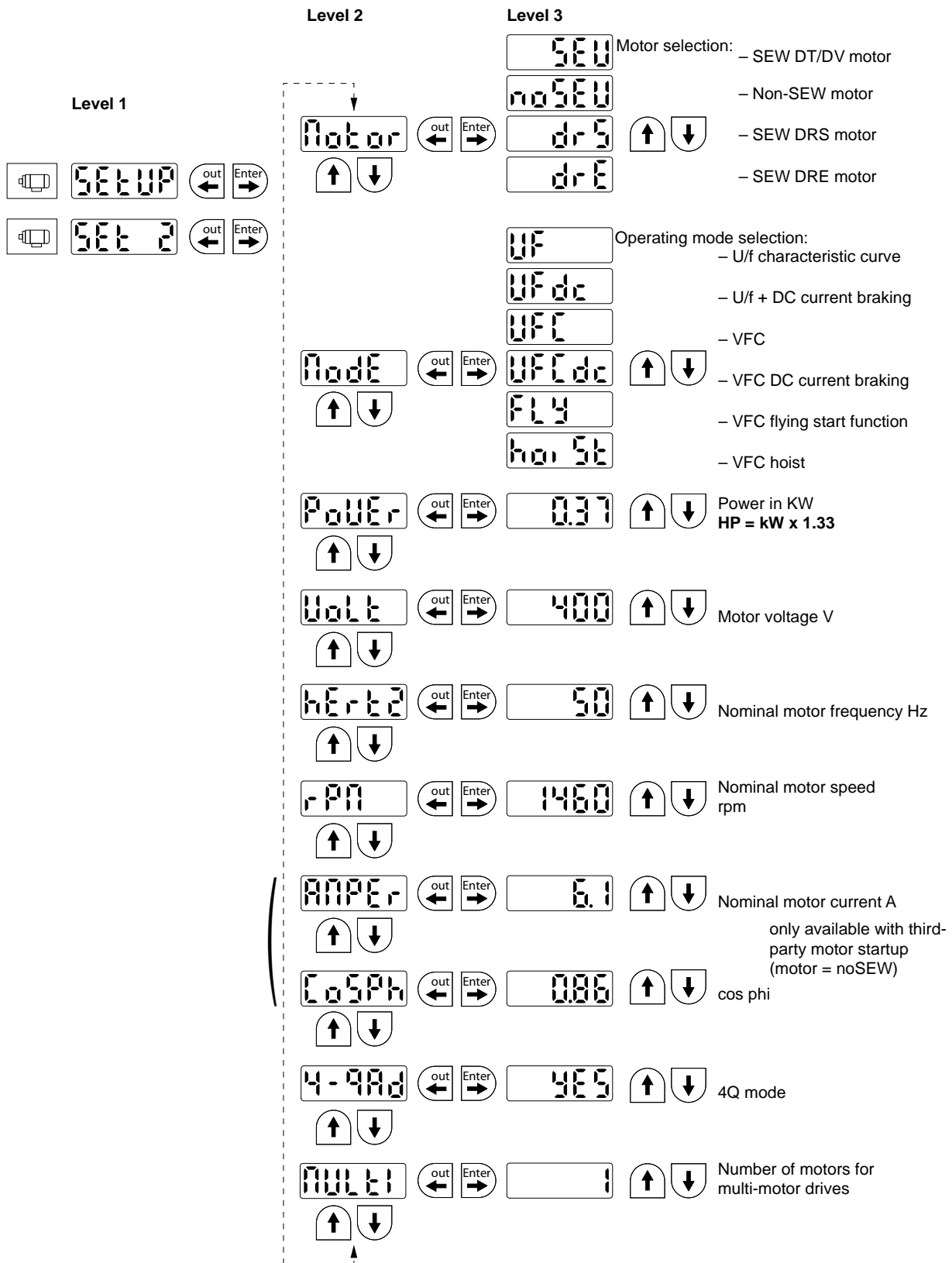
The `stop` display flashes to indicate that you have to re-enable the drive via the RUN button.

The parameter *P760 Locking RUN/STOP keys* does not have any effect in "manual speed control module" operating mode.

Removing the FBG11B keypad will trigger a stop response.



5.3 Startup using the FBG11B keypad



27021597782442891



Startup

Startup using the FBG11B keypad

5.3.1 Required data

The following data is required to ensure startup is successful:

- Motor type (SEW or non-SEW motor)
- Motor data
 - Rated voltage and rated frequency
 - Additionally for non-SEW motors: Nominal current, nominal power, power factor $\cos \phi$, and nominal speed.
- Rated line voltage

5.3.2 Activating startup

Requirements:

- Drive "no enable": Stop

If a smaller or a larger motor is connected (maximum difference one size), then you have to choose the value closest to the rated motor power.

The startup procedure is not complete until you have returned to the main menu level by pressing the OUT button.

You can then perform startup only with motor parameter set 1.



INFORMATION

The SEW motor startup is designed for 4-pole motors. It may be useful to start up 2-pole or 6-pole SEW motors as non-SEW motors.

5.3.3 Operating mode V/f

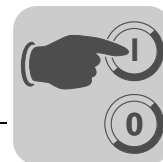
The default setting for the operating mode is V/f. Use this operating mode if you have no particular speed quality requirements and for applications that require a maximum output frequency > 150 Hz.

5.3.4 Operating mode VFC

Start up the inverter in VFC or VFC & DC brake operating mode for the following requirements:

- High torque
- Continuous duty at low frequencies
- Accurate slip compensation
- More dynamic behavior

For this purpose, you will have to choose the VFC or VFC & DC brake operating modes from P01 at startup.



5.3.5 Multi-motor drive startup

Multi-motor drives are mechanically coupled to each other (e.g. chain drive with multiple motors).

Observe the notes in the "MOVIDRIVE® Multi-Motor Drives" manual.

5.3.6 Group drive startup

Group drives are mechanically decoupled from each other (e.g. different conveyor belts). In this operating mode, the inverter operates without slip compensation and with a constant V/f ratio.

Observe the notes in the "MOVIDRIVE® Multi-Motor Drives" manual.

5.3.7 Startup with large load mass moment of inertia, such as with pumps and fans

The slip compensation is designed for a load mass moment of inertia to motor moment of inertia ratio smaller than 10. If the ratio is larger and the drive vibrates, then slip compensation must be reduced and even be set to 0 if necessary.



5.4 Parameter list

All parameters that can also be displayed and edited using the keypad are indicated as follows in the "FBG" (keypad) column:



Selection in the long menu (*P800* = long)



Selection in the short or long menu (*P800* = short)









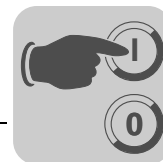
Display in the pictogram menu in the FBG11B keypad







Selection within FGB motor startup

If there are several options, the factory setting is underlined.

No.	FBG	Index dec.	Name	Range / factory setting	
			Display	MOVITOOLS® MotionStudio	
0..	Display values (read only)				
00.			Process values		
000		8318	Speed (signed)		rpm
001		8501	User display for DBG11B		Text
002		8319	Frequency (signed)		Hz
004		8321	Output current (absolute value)		% I _N
005		8322	Active current (signed)		% I _N
008		8325	DC link voltage		V
009		8326	Output current		A
01.	Status displays				
010		8310	Inverter state		Text
011		8310	Operating state		Text
012		8310	Error status		Text
013		8310	Current parameter set		Current parameter set
014		8327	Heat sink temperature		°C
02.	Analog setpoints				
020		8331	Analog input AI1		V
021		8332	Analog input AI2 (optional)		V
03.	Binary inputs (see parameter P60.)				
030		8844	Binary input DI00		<u>Error reset</u>
031		8335	Binary input DI01		CW / STOP (fixed assignment)
032		8336	Binary input DI02		<u>CCW/stop</u>
033		8337	Binary input DI03		<u>Enable/stop</u>
034		8338	Binary input DI04		<u>n11/n21</u>
035		8339	Binary input DI05		<u>n12/n22</u>



No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
039		8334	Binary inputs DI00 – DI05		Collective display of binary inputs
04.	Binary inputs option (see parameter P60.)				
040			Binary input DI10		<u>No function</u>
041			Binary input DI11		<u>No function</u>
042			Binary input DI12		<u>No function</u>
043			Binary input DI13		<u>No function</u>
044			Binary input DI14		<u>No function</u>
045			Binary input DI15		<u>No function</u>
046			Binary input DI16		<u>No function</u>
048		8348	Binary inputs DI10 – DI15		Collective display of binary inputs
05.	Binary outputs (see parameter P62.)				
051		8349	Binary output DO01		<u>/Fault</u>
052		8349	Binary output DO02		<u>Brake released</u>
053		8349	Binary output DO03		<u>Ready</u>
059		8349	Binary outputs DO01 – DO03		Collective display of binary outputs
07.	Unit data				
070		8301	Unit type		Text
071		8361	Nominal output current		A
073		8362	Front module		
073		8364	Firmware front module		
076		8300	Basic unit firmware		Part number and version
077		–	DBG firmware		Only in DBG60B
08.	Error memory				
080 – 084		8366 – 8370	Error t-0 – t-4	Error code	Background information for previous errors.



Startup Parameter list

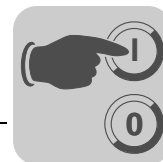
No.	FBG	Index dec.	Name	Range / factory setting		
				Display	MOVITOOLS® MotionStudio	
09.	Bus diagnostics					
090	Long	8451	PD configuration			
091		8452	Fieldbus type			
092		8453	Fieldbus baud rate			
093		8454	Fieldbus address			
094		8455	PO 1 setpoint		hex	
095		8456	PO 2 setpoint		hex	
096		8457	PO 3 setpoint		hex	
097		8458	PI 1 actual value		hex	
098		8459	PI 2 actual value		hex	
099		8460	PI 3 actual value		hex	
–		10497.1	Bus status			
		10497.3	Device identification			
1..	Setpoints / ramp generators (on FBG only parameter set 1)					
10.	Setpoint selection / frequency input					
100	Short	8461	Setpoint source	0 1 2 4 6 7 8 9 10 11 14	Bipolar / fixed setpoint <u>Unipolar / fixed setpoint</u> RS485/fixed setpoint Motor potentiometer / fixed setpoint Fixed setpoint + AI1 Fixed setpoint* + AI1 MASTER SBus1 MASTER RS485: SBus 1/fixed setpoint Frequency setpoint input/fixed setpoint Bipolar AI2 / Fixed setpoint	
101		8462	Control signal source	0 1 3 4	<u>Terminals</u> RS485 SBus 1 3-wire control	
102		8840	Frequency scaling	0.1 – <u>10</u> – 120.00 kHz		
103		10247.15	FI1 reference	0 1	<u>n_{max}</u> n _{reference}	
104		10247.10	Setpoint reference speed n _{reference}	0 – <u>3000</u> – 6000 rpm		
105		10416.1	Wire breakage detection	0 2 4 7	No response Immediate stop/malfunction Rapid stop/malfunction <u>Rapid stop/warning</u>	
106		Long	10247.11	FI1 char. curve x1	<u>0</u> – 100 %	
107			10247.12	FI1 char. curve y1	–100 % – <u>0</u> – +100 %	
108			10247.13	FI1 char. curve x2	0 – <u>100 %</u>	
109			10247.14	FI1 char. curve y2	–100 % – 0 – <u>+100 %</u>	



No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
11.	Analog input 1 (0 – 10 V)				
112		8465	AI1 operating mode	<u>1</u> 5 6 7 8 9	<u>10 V, reference potential maximum speed</u> 0 – 20 mA, reference maximum speed 4 – 20 mA, reference maximum speed 0 – 10 V, n-reference 0 – 20 mA, n-reference 4 – 20 mA, n-reference
116		10247.6	AI1 char. curve x1	<u>0</u> – 100 %	
117		10247.7	AI1 char. curve y1	–100 % – <u>0</u> – +100 %	
118		10247.8	AI1 char. curve x2	0 – <u>100</u> %	
119		10247.9	AI1 char. curve y2	–100 % – 0 – <u>+100</u> %	
12.	Analog input AI2 / FBG speed control module (option)				
120		8469	AI2 operating mode	<u>0</u> 1 2	<u>No function</u> 0 – ±10 V + setpoint 0 – 10 V current limit
121		8811	Addition FBG speed control module	<u>0</u> 1 2	<u>Off</u> On On (without fixed setpoint)
122		8799	Direction of rotation FBG manual operation	<u>0</u> 1 2	<u>Unipolar CW</u> Unipolar CCW Bipolar CW and CCW
126		10247.1	AI2 char. curve x1	<u>–100</u> % – 0 – +100 % (<u>–10 V</u> – 0 – +10 V)	
127		10247.2	AI2 char. curve y1	<u>–100</u> % – 0 – +100 % (<u>–n_{max}</u> – 0 – +n _{max} / <u>0</u> – I _{max})	
128		10247.3	AI2 char. curve x2	–100 % – 0 – <u>+100</u> % (<u>–10 V</u> – 0 – <u>+10 V</u>)	
129		10247.4	AI2 char. curve y2	–100 % – 0 – <u>+100</u> % (<u>–n_{max}</u> – 0 – <u>+n_{max}</u> / 0 – I _{max})	
13. / 14.	Speed ramps 1 / 2				
130 / 140		8807 / 9264	Ramp t11/t21 up	0.1 – <u>2</u> – 2000 s	
131 / 141		8808 / 9265	Ramp t11 / t21 down	0.1 – <u>2</u> – 2000 s	
134 / 144		8474 / 8482	Ramp t12 / t22	0.1 – <u>10</u> – 2000 s	
135 / 145		8475 / 8483	S pattern t12 / t22	<u>0</u> 1 2 3	<u>Off</u> Weak Medium Strong
136 / 146		8476 / 8484	Stop ramp t13 / t23	0.1 – <u>2</u> – 20 s	
139 / 149		8928 / 8929	Ramp monitoring 1 / 2	<u>0</u> 1	<u>YES</u> NO
15.	Motor potentiometer				
150		8809	Ramp t3 up = down	0.2 – <u>20</u> – 50 s	
152		8488	Save last setpoint	<u>off</u> on	<u>Off</u> On



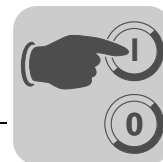
No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
16. / 17.	Fixed setpoints				
160 / 170		8489 / 8492	Internal setpoint n11 / n21	0 – <u>150</u> – 5000 rpm	
161 / 171		8490 / 8493	Internal setpoint n12 / n22	0 – <u>750</u> – 5000 rpm	
162 / 172		8491 / 8494	Internal setpoint n13 / n23	0 – <u>1500</u> – 5000 rpm	
163 / 173		8814 / 8817	n11/n21 PI control- ler	0 – <u>3</u> – 100 %	
164 / 174		8815 / 8818	n12/n22 PI control- ler	0 – <u>15</u> – 100 %	
165 / 175		8816 / 8819	n13/n23 PI control- ler	0 – <u>30</u> – 100 %	
2..	Controller parameters				
25.	PI controller				
250		8800	PI controller	<u>0</u> 1 2	Off Normal Inverted
251		8801	PI gain	0 – <u>1</u> – 64	
252		8802	I component	0 – <u>1</u> – 2000 s	
3..	Motor parameters (on FBG only parameter set 1)				
30. / 31.			Limits 1 / 2		
300 / 310		8515 / 8519	Start/stop speed 1 / 2	0 – 150 rpm	
301 / 311		8516 / 8520	Minimum speed 1 / 2	0 – <u>15</u> – 5500 rpm	
302 / 312		8517 / 8521	Maximum speed 1 / 2	0 – <u>1500</u> – 5500 rpm	
303 / 313		8518 / 8522	Current limit 1 / 2	0 – <u>150</u> % I _N	
32. / 33.	Motor adjustment 1 / 2				
320 / 330		8523 / 8528	Automatic adjust- ment 1/2	<u>oFF</u> <u>on</u>	Off <u>On</u>
321 / 331		8524 / 8529	Boost 1/2	0 – 100 %	
322 / 332		8525 / 8530	IxR compensation 1/2	0 – 100 %	
323 / 333		8526 / 8531	Premagnetization time 1 / 2	0 – 2 s	
324 / 334		8527 / 8532	Slip compensation 1 / 2	0 – 500 rpm	
34.	I _N UL monitoring				
340		8533	Motor protection 1	<u>OFF</u> / ON ASYNCHRONOUS / ON SERVO	
341		8534	Cooling type 1	<u>FAN COOLED</u> / FORCED COOLING	
342		8535	Motor protection 2	<u>OFF</u> / ON ASYNCHRONOUS / ON SERVO	
343		8536	Cooling type 2	<u>FAN COOLED</u> / FORCED COOLING	
345 / 346		9114 / 9115	I _N UL monitoring 1 / 2	0.1 – 500 A	









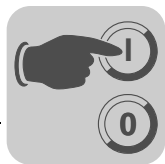
No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
4..	Reference messages				
40.	Speed reference signal				
400	Long	8539	Speed reference value	0 – <u>750</u> – 5000 rpm	
401		8540	Hysteresis	0 – <u>100</u> – +500 rpm	
402		8541	Deceleration time	0 – <u>1</u> – 9 s	
403		8542	Message = "1" if:	<u>0</u> 1	$n < n_{ref}$ $n > n_{ref}$
43.	Current reference signal				
430	Long	8550	Current reference value	0 – <u>100</u> – 150 % I _N	
431		8551	Hysteresis	0 – <u>5</u> – 30 % I _N	
432		8552	Deceleration time	0 – <u>1</u> – 9 s	
433		8553	Signal = "1" when	<u>0</u> 1	$I < I_{ref}$ $I > I_{ref}$
44.	I _{max} signal				
440	Long	8554	Hysteresis	0 – <u>5</u> – 50 % I _N	
441		8555	Deceleration time	0 – <u>1</u> – 9 s	
442		8556	Signal = "1" when	<u>0</u> 1	$I < I_{max}$ $I > I_{max}$
45.	PI controller reference message				
450	Long	8813	PI actual value reference	<u>0.0</u> – 100.0 %	
451		8796	Message = "1" if:	<u>0</u> <u>1</u>	PI Actual value < PI ref PI Actual value > PI ref
5..	Control functions (on FBG only parameter set 1)				
50.	Speed monitoring 1 / 2				
500 / 502	Long	8557 / 8559	Speed monitoring 1 / 2	<u>0</u> 3	Off Motor/regenerative
501 / 503		8558 / 8560	Delay time 1/2	0 – <u>1</u> – 10 s	
54.	Gear unit/motor monitoring				
540	Long	9284	Response to drive vibration/warning	<u>1</u>	Display error
541		9285	Response to drive vibration/error	<u>1</u>	Rapid stop/warning
542		9286	Response to oil aging/error	<u>1</u>	Display error
543		9287	Response to oil aging/warning	<u>1</u>	Display error
544		9288	Oil aging / overtemperature	<u>1</u>	Display error
545		9289	Oil aging / ready signal	<u>1</u>	Display error
549		9290	Response to brake wear	<u>1</u>	Display error












No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
56.			Ex-e motor current limitation		
560		9293	Ex-e motor current limit		ON / <u>OFF</u>
561		9294	Frequency A		0 – <u>5</u> – 60 Hz
562		9295	Current limit A		0 – <u>50</u> – 150 %
563		9296	Frequency B		0 – <u>10</u> – 104 Hz
564		9297	Current limit B		0 – <u>80</u> – 200 %
565		9298	Frequency C		0 – <u>25</u> – 104 Hz
566		9299	Current limit C		0 – <u>100</u> – 200 %
567		10247.20	Frequency D		0 – <u>50</u> – 104 Hz
568		10247.21	Current limit D		0 – <u>100</u> – 200 %
57.			Motor protection		
570		10247.22	Frequency E		0 – <u>87</u> – 104 Hz
571		10247.23	Current limit E		0 – <u>100</u> – 200 %
6..			Terminal assignment		
60.			Binary inputs		
601		8336	Binary input DI02 assignment	0: No function 1: Enable / stop (factory setting DI03) 2: CW/stop 3: CCW / stop (factory setting DI02) 4: n11/n21 (factory setting DI04) 5: n12/n22 (factory setting DI05) n13 = n11 + n12 6: Changing the fixed setpoint 7: Parameter set switchover 8: Ramp switchover 9: Motor potentiometer up 10: Motor potentiometer down 11: /External error 12: Error reset (factory setting DI00) 19: Slave free running 20: Setpoint acceptance active 26: TF signal (only with DI05) 27: Vibration/warning 28: Vibration/error 29: Brake wear 30: Controller inhibit 33: Oil aging/warning 34: Oil aging/error 35: Oil aging / overtemperature 36: Oil aging/ready	
602		8337	Binary input DI03 assignment		
603	Short	8338	Binary input DI04 assignment		
604		8339	Binary input DI05 assignment		
608		8844	Binary input DI00 assignment		
61.			Binary inputs option		
610		8340	Binary input DI10 assignment		
611		8341	Binary input DI11 assignment		
612	Short	8342	Binary input DI12 assignment		
613		8343	Binary input DI13 assignment		
614		8344	Binary input DI14 assignment		
615		8345	Binary input DI15 assignment		
616		8346	Binary input DI16 assignment		

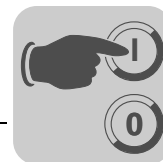








No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
62.	Binary outputs				
620		8350	Binary output DO01 assignment	0	No function
621		8351	Binary output DO02 assignment	1	<u>/Malfunction</u> (factory setting DO01)
622		8916	Binary output DO03 assignment	2	<u>Ready</u> (factory setting DO03)
				3	Output stage ON
				4	Rotating field ON
				5	<u>Brake released</u> (factory setting DO02 / Not with DO03)
				8	Parameter set
				9	Speed reference signal
				11	Setpoint-actual value comparison signal
				12	Current reference message
				13	I _{max} signal
				21	IPOS output
				22	/IPOS fault
				23	PI controller actual value reference
				24	Ex-e current limit active
				27	Safe stop
				30	Ixt warning
				31	Ixt fault
64.	Analog outputs AO1 (optional)				
640		8568	AO1 analog output	0	<u>No function</u>
				1	Ramp generator input
				2	Setpoint speed
				3	Actual speed
				4	Actual frequency
				5	Output current
				6	Active current
				7	Unit utilization
				11	Actual speed (signed)
				12	Actual frequency (signed)
641		10248.5	AO1 reference	0	<u>3000 rpm, 100 Hz, 150%</u>
				1	n _{max}
				2	n _{set} reference
642		8570	AO1 Operating mode	0	<u>No function</u>
				2	0 – 20 mA
				3	4 – 20 mA
				4	0 – 10 V
646		10246.1	AO1 char. curve x1	–100 % – 0 – +100 %	
647		10246.2	AO1 char. curve y1	<u>–100</u> – 100 %	
648		10246.3	AO1 char. curve x2	–100 % – 0 – <u>+100 %</u>	
649		10246.4	AO1 char. curve y2	–100 – <u>100 %</u>	
7..	Control functions (on FBG only parameter set 1)				
70.	Operating modes 1 / 2				
700 / 701		8574 / 8575	Operating mode 1 / 2	0	VFC
				2	VFC & Hoist
				3	VFC & DC braking
				4	VFC & flying start function
				21	<u>V/f characteristic curve</u>
				22	V/f & DC braking



Startup Parameter list

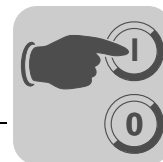
No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
71.			Standstill current 1 / 2		
710 / 711		8576 / 8577	Standstill current 1 / 2	<u>0</u> – 50% I _{Mot}	
72.			Setpoint stop function 1 / 2		
720 / 723		8578 / 8581	Setpoint stop function 1 / 2	<u>oFF</u> on	<u>Off</u> On
721 / 724		8579 / 8582	Stop setpoint 1 / 2	0 – <u>30</u> – 500 rpm	
722 / 725		8580 / 8583	Start offset 1 / 2	0 – <u>30</u> – 500 rpm	
73.			Brake function 1 / 2		
731 / 734		8749 / 8750	Brake release time 1 / 2	<u>0</u> – 2 s	
732 / 735		8585 / 8587	Brake application time 1 / 2	0 – 2 s	
74.			Speed skip function		
740 / 742		8588 / 8590	skip window center 1 / 2	0 – <u>1500</u> – 5000 rpm	
741 / 743		8589 / 8591	skip width 1 / 2	<u>0</u> – 300 rpm	
75.			Master-slave function		
750		8592	Slave setpoint	<u>0</u> 1 2 3	<u>Master/slave off</u> Speed RS485 Speed SBus Speed RS485 + SBus
751		8593	Scaling slave setpoint		<u>1.00</u>
76.			Manual operation		
760		8798	Lock RUN / STOP / RESET keys	<u>oFF</u> on	<u>Off</u> On
77.			Energy-saving function		
770		8925	Energy-saving function	<u>oFF</u> on	<u>Off</u> On
8..			Unit functions (on FBG only parameter set 1)		
80.			Setup		
800		–	Quick menu	long <u>Short</u>	
801		–	DBG language		
802		8594	Factory setting	<u>No</u> Hours ALL NEMA	<u>No</u> Standard Delivery state Delivery state NEMA
803		8595	Parameter lock	<u>oFF</u> on	<u>Off</u> On
804		8596	Reset statistics data	–	<u>No action</u> Error memory
805		8660	Rated line voltage		50 – 500 V



No.	FBG	Index dec.	Name	Range / factory setting	
				Display	MOVITOOLS® MotionStudio
806		–	Copy DBG → MOVITRAC® B		Yes <u>No</u>
807		–	Copy MOVITRAC® B → DBG		Yes <u>No</u>
808		10204.3	24 V output voltage	Off On	Off <u>On</u>
809		10204.1	IPOS enable	–	<u>Off</u> On
81.	Serial communication				
810		8597	RS485 address	<u>0</u> – 99	
811		8598	RS485 group address	<u>100</u> – 199	
812		8599	RS485 Timeout interval	<u>0</u> – 650 s	
819		8606	Fieldbus timeout interval	Fieldbus timeout interval display	
82.	Brake operation 1 / 2				
820 / 821		8607 / 8608	4-quadrant operation 1/2	oFF <u>on</u>	Off <u>On</u>
83.	Error responses				
830		8609	Response terminal "external error"	2 4 <u>7</u>	Immediate stop/malfunction
833		8612	Response timeout RS485		<u>Rapid stop / Malfunction</u> (Factory setting for P830)
836		8615	Response to SBus timeout		<u>Rapid stop / Warning</u> (Factory setting for P833 / P836)
84.	Reset behavior				
840		8617	Manual reset		Yes <u>No</u>
841		8618	Auto reset	Off On	<u>Off</u> On
842		8619	Restart time		1 – <u>3</u> – 30 s
85.	Scaling actual speed value				
850		8747	Scaling factor numerator	<u>1</u> – 65535 (can be set with SHELL only)	
851		8748	Scaling factor denominator	<u>1</u> – 65535 (can be set with SHELL only)	
852		8772 / 8773	User unit	Text	
853		9312	Scaled speed FBG	<u>0</u> 1	<u>Speed</u> Scaled speed



No.	FBG	Index dec.	Name	Range / factory setting		
				Display	MOVITOOLS® MotionStudio	
86.		Modulation 1 / 2				
860 / 861	Long	8620 / 8621	PWM frequency 1 / 2	4 8 12 16	4 kHz 8 kHz 12 kHz 16 kHz	
862 / 863		8751 / 8752	PWM fix 1 / 2	on oFF	On Off	
87.		Process data parameter setting				
870	Long	8304	Setpoint description PO1	0 1 5 8 9 10 11 12 13	No function (factory setting P872) Setpoint speed (factory setting P871) Max. speed Ramp Control word 1 (factory setting P870) Control word 2 Setpoint speed % IPOS PO data PI controller setpoint %	
871		8305	Setpoint description PO2			
872		8306	Setpoint description PO3			
873		8307	Actual value description PI1	0 1 2 3 6 7 8 9 10	No function Actual speed (factory setting P874) Output current (factory setting P875) Active current Status word 1 (factory setting P873) Status word 2 Actual speed % IPOS PI-DATA PI controller actual value %	
874		8308	Actual value description PI2			
875		8309	Actual value description PI3			
876		Long	8622	PO data enable	No Yes	No Yes
88.			Serial communication SBus			
880		Long	8937	SBus protocol	0 / MOVILINK 1 / CANopen	
881			8600	SBus address	0 – 63	
882			8601	SBus group address	0 – 63	
883		Long	8602	SBus timeout interval	0 – 650 s	
884			8603	SBus baud rate	125 250 500 1000	125 kBd 250 kBd 500 kBd 1 Mbaud
886			8989	CANopen address	1 – 2 – 127	



6 Operation

6.1 Return codes (r-19 – r-38)

Return codes when entering / editing a unit parameter in the FBG11B:

No.	Designation	Meaning
18	Only read access	Parameter cannot be changed
19	Parameter lock activated	Parameters cannot be changed
20	Factory setting in progress	Parameters cannot be changed
23	Option card missing	The option card required for the function is missing.
27	Option card missing	The option card required for the function is missing.
28	Controller inhibit required	Controller inhibit required
29	Invalid value for parameter.	<ul style="list-style-type: none"> Invalid value for parameter. FGB manual operation selection invalid as PC is in active manual operation.
32	Enabled	You cannot perform this function in ENABLED status
34	Error in sequence	<ul style="list-style-type: none"> Error while saving in FBG11B. Startup not performed with FBG. Perform startup with MotionStudio or select a new motor.
38	FBG11B incorrect data set	Stored data set does not match the unit



6.2 Status displays

6.2.1 Basic unit / keypad FBG11B

The status displays on the unit are as follows:

State	Display (optionally with FBG11B key pad)	Basic unit status LED flash code	Unit status (high byte in status word 1)
"ENABLE"	Speed	Constant green light	4
"ENABLE" at current limit	Speed flashes	Rapid green flashing	
"CURRENT AT STAND-STILL"	dc	Slow green flashing	3
"NO ENABLE"	Stop	Constant yellow light	2
"FACTORY SETTING"	SEt	Rapid yellow flashing	8
"CONTROL.INHIBIT"	oFF	Rapid yellow flashing	1
"24 V operation"	24U flashing	Slow yellow flashing	0
"SAFE STOP" ¹⁾	U flashing or 24U flashing	Slow yellow flashing	17
FBG manual mode active or inverter stopped using STOP button.	FBG manual operation symbol or "stop" is flashing	Yellow on long, off briefly	
Timeout	Errors 43 / 47	Flashing green/yellow	
Copy	Error 97	Flashing red/yellow	
System error	Error 10 / 17 – 24 / 25 / 32 / 37 / 38 / 45 / 77 / 80 / 94	Constant red light	
Overvoltage / phase failure	Errors 4 / 6 / 7	Slow red flashing	
Overload	Errors 1 / 3 / 11 / 44 / 84	Rapid red flashing	
Monitoring	Errors 8 / 26 / 34 / 81 / 82	2 x red flashing	
Motor protection	Errors 31 / 84	3 x red flashing	

1) "U" flashing (status 17) if connected to supply system, "24U" flashing (status 0) if in backup mode.

- ▲ WARNING** Incorrect interpretation of display U = "Safe stop" active.
 Severe or fatal injuries.
 - The display U = "Safe stop" is not safety-related and must not be used as a safety function.



Cause for controller inhibit (OFF)

The controller inhibit (OFF) can be caused by the following conditions:

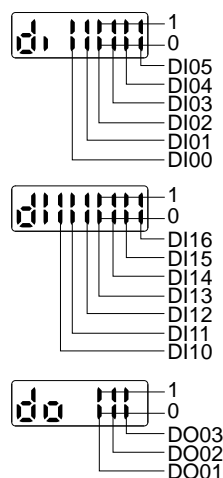
- Binary input terminal (DI00, DI02 – DI05) programmed to controller inhibit and activated.
- Controller inhibit due to PC manual mode via MOVITOOLS® MotionStudio.
- Temporary controller inhibit: Is triggered if a change of parameter *P100 setpoint source* would directly cause an enable signal. The temporary controller inhibit is removed once the enable signal is reset for the first time.
- Controller inhibit set via IPOS control word H484.

6.2.2 Status of binary inputs / outputs

The following parameters are available in the parameter menu as display parameters:

- *P039 Binary inputs of basic unit*
- *P048 Binary inputs option*
- *P059 binary outputs*

The status is displayed as binary. Every binary input or output has two segments vertically on top of one another of the 7-segment display assigned to it. The upper segment lights up when the binary input or output is set, and the lower segment lights up when the binary input or output is not set. The two 7-segment displays on the right indicate whether *P039* (di = binary inputs basic unit), *P048* (di = binary inputs option), or *P059* (do = binary outputs) are output.



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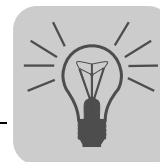
If no FIO21B with binary inputs is available, the display will show d1 - - -.



7 Service / List of Errors

7.1 Error list (F-00 – F113)

No.	Designation	Response	Possible cause	Measure
00	No error	–	–	–
01	Overcurrent	Immediate switch-off with inhibit.	• Short circuit at output	• Rectify the short circuit
			• Switching at the output	• Switching with inhibited output stage only
			• Motor too large	• Connect a smaller motor
			• Faulty output stage	• Consult SEW Service if the error cannot be reset
03	Ground fault	Immediate switch-off with inhibit.	• Ground fault in motor	• Replace motor
			• Ground fault in inverter	• Replace the MOVITRAC® B
			• Ground fault in the motor supply lead	• Eliminate ground fault
			• Overcurrent (see F01)	• See F01
04	Brake chopper	Immediate switch-off with inhibit.	• Too much regenerative power	• Extend deceleration ramps
			• Braking resistor circuit interrupted	• Check supply cable to the braking resistor
			• Short circuit in the braking resistor circuit	• Rectify the short circuit
			• Brake resistance too high	• Check technical data of braking resistor
			• Brake chopper defective	• Replace the MOVITRAC® B
			• Ground fault	• Eliminate ground fault
06	Mains phase failure	Immediate switch-off with inhibit (only with 3-phase inverter)	• Phase failure	• Check the line cable
			• Supply voltage too low	• Check the supply voltage
07	DC link over-voltage	Immediate switch-off with inhibit.	• DC link voltage too high	• Extend deceleration ramps • Check supply cable to the braking resistor • Check technical data of braking resistor
			• Ground fault	• Eliminate ground fault
08	Speed monitoring	Immediate switch-off with inhibit.	Current controller works at the set limit due to:	–
			• Mechanical overload	• Reduce load • Check current limitation • Extend deceleration ramps • Increase set deceleration time P501 ¹⁾
			• Phase failure in supply system	• Check line phases
			• Phase failure in motor	• Check motor cable and motor
			• Maximum speed for VFC operating modes exceeded	• Reduce maximum speed
09	Startup	Immediate switch-off with inhibit.	• Inverter not started yet	• Start up the inverter
			• Unknown motor selected	• Select another motor
10	IPOS-ILLOP	Stop with inhibit With IPOS only	• Wrong command during program execution	• Check the program
			• Incorrect conditions during program execution.	• Check program run
			• Function does not exist / is not implemented in the inverter	• Use another function



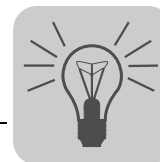
No.	Designation	Response	Possible cause	Measure
11	Overtemperature	Stop with inhibit	<ul style="list-style-type: none"> Thermal overload of inverter 	<ul style="list-style-type: none"> Reduce load and/or ensure adequate cooling If a braking resistor is integrated in the heat sink: Install braking resistor externally
17 – 24	System malfunction	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Inverter electronics is faulty, possibly due to EMC influence 	<ul style="list-style-type: none"> Check grounding and shielding and improve, if necessary Contact SEW Service for advice if this error reoccurs.
25	EEPROM	Stop with inhibit	<ul style="list-style-type: none"> Error while accessing EEPROM 	<ul style="list-style-type: none"> Restore factory settings, perform reset and reset parameters. Consult SEW Service if the error reoccurs
26	External terminal	Programmable	<ul style="list-style-type: none"> Read in external error signal via programmable input. 	<ul style="list-style-type: none"> Eliminate respective cause; reprogram terminal if necessary
31	TF/TH sensor tripped	Stop without inhibit <ul style="list-style-type: none"> "Ready" signal is maintained 	<ul style="list-style-type: none"> Motor too hot, TF sensor has tripped TF sensor of motor not connected or connected incorrectly Connection of MOVITRAC® B and TF on motor interrupted 	<ul style="list-style-type: none"> Let motor cool off and reset error Check connections / links between MOVITRAC® B and TF
32	IPOS index overflow	Stop with inhibit	<ul style="list-style-type: none"> Programming principles violated leading to internal stack overflow 	<ul style="list-style-type: none"> Check user program and correct it
34	Ramp timeout	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Set ramp time exceeded. If you remove the inhibit and the drive exceeds the stop ramp time t13 by a certain time, the inverter will signal F34 	<ul style="list-style-type: none"> Extend the ramp time Extend the stop ramp time
35	Ex-e protection operating mode	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Wrong operating mode selected Non-permitted parameter set No Ex-e motor started up Incorrect parameterization of the frequency points Incorrect parameterization of the current limits 	Permitted modes: <ul style="list-style-type: none"> V/f, VFC, VFC hoist Incorrect modes: <ul style="list-style-type: none"> Flying start function DC braking Group operation <ul style="list-style-type: none"> Use parameter set 1 only Start up Ex-e motor Frequency A < frequency B Frequency B < frequency C Current limit A < current limit B Current limit B < current limit C
36	Option missing	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Type of option card not allowed Setpoint source, control signal source or operating mode not permitted for this option card Required option missing Front module FIO21B not supplied 	<ul style="list-style-type: none"> Use correct option card Set correct setpoint source. Set correct control signal source Set the correct operating mode. Check parameters P120 and P121 Check the following parameters: <ul style="list-style-type: none"> P121 for FBG11B P120 and P642 for FIO12B Set P808 to "On" or supply basic unit with external 24 V
37	System watchdog	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Fault in system software sequence 	<ul style="list-style-type: none"> Check grounding and shielding and improve, if necessary Contact SEW Service for advice if this error reoccurs.



Service / List of Errors

Error list (F-00 – F113)

No.	Designation	Response	Possible cause	Measure
38	System software	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> System malfunction 	<ul style="list-style-type: none"> Check grounding and shielding and improve, if necessary Contact SEW Service for advice if this error reoccurs.
43	RS485 timeout	Stop without locking ²⁾	<ul style="list-style-type: none"> Connection between inverter and PC interrupted. Communication to FSE24B interrupted 	<ul style="list-style-type: none"> Check connection between inverter and PC Check voltage supply Check P808
44	Unit utilization	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Unit utilization ($I \times t$ value) exceeded 	<ul style="list-style-type: none"> Decrease power output Extend ramps If neither is possible: Use a larger inverter
45	Initialization	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Error during initialization 	<ul style="list-style-type: none"> Contact SEW Service.
47	System bus 1 timeout	Stop without inhibit ²⁾	<ul style="list-style-type: none"> Error during communication via system bus 	<ul style="list-style-type: none"> Check system bus connection Check P808 Check voltage supply of FSE24B Check EtherCAT communication with connected FSE24B
77	IPOS control word	Stop with inhibit	<ul style="list-style-type: none"> System malfunction 	<ul style="list-style-type: none"> Contact SEW Service.
80	RAM test	Immediate disconnection	<ul style="list-style-type: none"> Internal unit error, RAM defective 	<ul style="list-style-type: none"> Contact SEW Service.
81	Start condition	Immediate switch-off with inhibit.	<p>Only in "VFC hoist" operating mode: The motor could not be supplied with the correct amount of current during the pre-magnetizing time:</p> <ul style="list-style-type: none"> Rated motor power too small in relation to rated inverter power Motor cable cross section too small 	<ul style="list-style-type: none"> Check connection between inverter and motor Check startup data and perform new startup, if necessary. Check cross section of motor cable and increase if necessary.
82	Open output	Immediate switch-off with inhibit.	<p>Only in "VFC hoist" operating mode:</p> <ul style="list-style-type: none"> 2 or all output phases interrupted Rated motor power too small in relation to rated inverter power 	<ul style="list-style-type: none"> Check connection between inverter and motor Check startup data and perform new startup, if necessary.
84	Motor protection	Stop with inhibit	<ul style="list-style-type: none"> Motor utilization too high. 	<ul style="list-style-type: none"> Check P345 / P346 I_N-UL monitoring Reduce load Extend ramps Longer rest periods
94	EEPROM checksum	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Defective EEPROM 	<ul style="list-style-type: none"> Contact SEW Service.
97	Copy error	Immediate switch-off with inhibit.	<ul style="list-style-type: none"> Parameter module is removed during copying process Switching off/on during copying process 	<p>Prior to acknowledgement:</p> <ul style="list-style-type: none"> Load factory setting or complete data set from parameter module
98	CRC error flash	Immediate disconnection	<ul style="list-style-type: none"> Internal unit error, flash memory defective. 	<ul style="list-style-type: none"> Send unit in for repair
100	Vibration/warning	Display error	<ul style="list-style-type: none"> Vibration sensor warning (see "DUV10A diagnostics unit" operating instructions) 	<ul style="list-style-type: none"> Determine cause for vibration, operation possible until F101



No.	Designation	Response	Possible cause	Measure
101	Vibration error	Rapid stop	<ul style="list-style-type: none"> Vibration sensor signals error 	<ul style="list-style-type: none"> SEW-EURODRIVE recommends that you remedy the cause of the vibrations immediately
102	Oil aging/warning	Display error	<ul style="list-style-type: none"> Oil aging sensor warns 	<ul style="list-style-type: none"> Schedule oil change
103	Oil aging/error	Display error	<ul style="list-style-type: none"> Oil aging sensor signals error 	<ul style="list-style-type: none"> SEW-EURODRIVE recommends that you change the gear unit oil immediately.
104	Oil aging/over-temperature	Display error	<ul style="list-style-type: none"> Oil aging sensor signals over-temperature 	<ul style="list-style-type: none"> Let oil cool down Check if the gear unit cools properly
105	Oil aging / ready signal	Display error	<ul style="list-style-type: none"> Oil aging sensor is not ready for operation 	<ul style="list-style-type: none"> Check voltage supply of oil aging sensor Check and, if necessary, replace the oil aging sensor
106	Brake wear	Display error	<ul style="list-style-type: none"> Brake lining worn 	<ul style="list-style-type: none"> Replace brake lining (see "Motors" operating instructions)
110	Ex-e protection	Emergency stop	<ul style="list-style-type: none"> Duration of operation below 5 Hz exceeded 	<ul style="list-style-type: none"> Check configuration Shorten duration of operation below 5 Hz
111	System bus (SBus) error	This error number signals the EtherCAT or fieldbus master that the communication between FSE24B and MOVITRAC® B is interrupted. MOVITRAC® B would detect error 47.		<ul style="list-style-type: none"> Check FSE24B plug connection
113	Analog input open circuit	Programmable	<ul style="list-style-type: none"> AI1 analog input open circuit 	<ul style="list-style-type: none"> Check wiring
116	Error application module <i>Suberror:</i> 14: Encoder error 29: Limit switch contacted 42: Lag error 78: Software limit switch reached			

- 1) Change parameters *P500 / P502* and *P501 / P503* to set the speed monitoring. The sagging of hoists cannot be avoided safely when monitoring is deactivated or the delay time is set too long.
- 2) No reset required, error message disappears after communication is reestablished.



7.2 SEW electronics service

7.2.1 Hotline

Call the Drive Service Hotline to talk to an SEW-EURODRIVE service specialist on 365 days a year, 24 hours a day.

Simply dial the prefix **01805** and then enter the key combination **SEWHELP**. Or simply dial **01805 739 4357**.

7.2.2 Sending a unit in for repair

Consult **SEW Electronics Service** if you are unable to rectify the error.

Please always specify the unit status code number when you contact the SEW electronics service so that our service personnel can assist you more effectively.

Provide the following information when sending the unit in for repair:

- Serial number (see nameplate)
- Type designation
- Short description of application (application, control via terminals or serial)
- Connected motor (motor voltage, star or delta connection)
- Nature of the fault
- Accompanying circumstances
- Your own presumptions as to what has happened
- Unusual events preceding the problem



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